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1. (Previously Presented) A method of controlling an automotive vehicle having a controllable suspension component, said vehicle having a first turning radius comprising:

applying brake-steer to at least one wheel to provide a second turning radius less than the first turning radius;

generating a suspension control signal in response to applying brake-steer; and articulating at least one wheel coupled to the controllable suspension component to provide a third turning radius of the vehicle less than the second turning radius.

- 2. (Previously Presented) A method as recited in claim 1 wherein applying brake-steer comprises applying at least one brake at a first wheel.
- 3. (Original) A method as recited in claim 1 wherein applying brake-steer comprises applying an increased drive torque to a second wheel relative to a first wheel.
- 4. (Currently Amended) A method as recited in claim 1 applying brake-steer comprises increasing [[the]] a normal load on a rear wheel.
- 5. (Currently Amended) A method as recited in claim 1 applying brake-steer comprises increasing [[the]] a normal load on a front wheel.
- 6. (Currently Amended) A method as recited in claim 1 further comprising detecting a parking mode and generating the applying brake-steer signal in response to a parking mode.
- 7. (Original) A method as recited in claim 6 wherein detecting a parking mode comprises detecting a parking mode in response to a vehicle speed.
- 8. (Original) A method as recited in claim 6 wherein detecting a parking mode comprises detecting a parking mode in response to a steering wheel angle.

- 9. (Original) A method as recited in claim 6 wherein detecting a parking mode comprises detecting a parking mode in response to a map correlating vehicle speed and a steering wheel rate to a parking/non-parking condition.
- 10. (Original) A method as recited in claim 6 wherein detecting a parking mode comprises detecting a parking mode in response to a driver-actuated switch.
- 11. (Original) A method as recited in claim 1 wherein articulating one wheel comprises articulating two wheels.
- 12. (Original) A method as recited in claim 11 wherein the two wheels are coupled to a solid axle.
- 13. (Currently Amended) A method as recited in claim 1 wherein articulating at least one wheel coupled to the <u>controllable</u> suspension <u>component</u> comprises articulating using a Hotchkiss suspension.
- 14. (Currently Amended) A method as recited in claim 1 wherein articulating at least one wheel coupled to the <u>controllable</u> suspension <u>component</u> comprises articulating using an electrically controllable bushing.
- 15. (Currently Amended) A method as recited in claim 1 wherein articulating at least one wheel coupled to the <u>controllable</u> suspension <u>component</u> comprises a solenoid actuated suspension component <u>locking mechanism</u>.
- 16. (Currently Amended) A method as recited in claim 1 wherein articulating at least one wheel coupled to the <u>controllable</u> suspension <u>component</u> comprises a locking mechanism with a compliant rear suspension mount.
  - 17. (Previously Presented) A vehicle having a turning radius comprising:
  - a suspension comprising a controllable suspension component; and
- a controller coupled to the controllable component, said controller programmed to determine a brake-steer condition and generate a suspension control signal in response to the brake-steer condition,

said controllable suspension component actuating in response to the control signal and reducing the turning radius of the vehicle in response to the suspension control signal.

- 18. (Original) A vehicle as recited in claim 17 wherein said controller is programmed to determine a brake-steer condition in response to a parking mode.
- 19. (Original) A vehicle as recited in claim 17 wherein said controller determines a parking mode in response to a vehicle speed.
- 20. (Original) A vehicle as recited in claim 17 wherein said controller determines a parking mode in response a steering wheel angle.
- 21. (Original) A vehicle as recited in claim 17 wherein said controller determines a parking mode in response to a vehicle speed and a steering angle.
- 22. (Original) A vehicle as recited in claim 17 wherein said controller determines a parking mode in response to a driver-actuated switch.
- 23. (Currently Amended) A vehicle as recited in claim 17 wherein said controller in [[said]] a parking mode controls a first positive torque to a first driven wheel and simultaneously controls a second positive torque greater than the first positive torque to a second wheel so that the turning radius of the vehicle is reduced.
- 24. (Original) A vehicle as recited in claim 17 wherein said suspension comprises a Hotchkiss suspension.
- 25. (Original) A vehicle as recited in claim 17 wherein said suspension component comprises an electrically controllable bushing.
- 26. (Currently Amended) A vehicle as recited in claim 17 wherein said suspension component comprises a toe link coupled to [[the]] an electrically controllable bushing.

- 27. (Currently Amended) A vehicle as recited in claim 17 wherein said suspension component comprises a solenoid actuated suspension component locking mechanism.
- 28. (Original) A vehicle as recited in claim 17 wherein said suspension component comprises a locking mechanism with a compliant rear suspension mount.
- 29. (Currently Amended) A vehicle as recited in claim 17 wherein said electrically controllable suspension component reducing reduces the turning radius of the vehicle by articulating at least one wheel.
- 30. (Currently Amended) A vehicle as recited in claim 17 wherein said electrically controllable suspension component reduces the turning radius of the vehicle by articulating at two wheels on an axle.